Sequential Click Prediction for Sponsored Search with Recurrent Neural Networks

(Zhang, et al. 2017)

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1. Introduction

2. Data Analysis on Sequential Dependency

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1. Introduction

Sequential Click prediction (Zhang, et al. 2017)

Goal : Estimating the click-through rate (CTR) of ads with sequential information

- Modeling sequential dependency between user's behaviors $\rightarrow \mathsf{RNN}$

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2. Data Analysis on Sequential Dependency











(c) CTR on users' first and subsequent submissions of a certain type of query.

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Figure: Sequential information

 The model have to learn sequential dependency between user behaviors by itself.

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Feature Construction

- Ad features
- User features
- Sequential feature
- We re-organize the input features along with the user dimension.

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Architecture



Figure: RNN training process with BPTT algorithm. Unfolding step is set to 3 in this figure.

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Model

$$\begin{aligned} \mathbf{h}(t) &= f(i(t)\mathbf{U}^T + \mathbf{h}(t-1)\mathbf{R}^T), \\ y(t) &= \sigma(\mathbf{h}(t)\mathbf{V}^T) \end{aligned}$$

- **R** : the recurrent connections between $\mathbf{h}(t-1)$ and $\mathbf{h}(t)$,
- f() : tanh function , $\sigma()$: sigmoid
- *i*(*t*) : Features correlated to user's current behavior.
- **h**(*t*) : Sequential information of user's previous behaviors.

Learning

• Loss (averaged cross entropy)

$$L = \frac{1}{M} \sum_{i=1}^{M} (-y_i \log(p_i) - (1 - y_i) \log(1 - p_i))$$

- $y_i \in \{0, 1\}$: labeled sample, p_i : the predicted click probability
- Learning Algorithm (Back Propagation Through Time : BPTT)

Learning Algorithm(BPTT)

• The gradient of the output layer :

$$e_o(t) = y(t) - l(t)$$

y(t) : the predicted click prob., $\mathsf{l}(t)$: the binary true label

• The weights(**V**) between the hidden layer(**h**(t)) and output (y(t)) :

$$\mathbf{V}(t+1) = \mathbf{V}(t) - \alpha \times e_o(t) \times \mathbf{h}(t)$$

• Gradients of errors :

$$\begin{split} \mathbf{e}_{\mathbf{h}}(t) &= \mathbf{e}_{o}(t)\mathbf{V}*(\overrightarrow{1}-\mathbf{h}(t)*\mathbf{h}(t)),\\ \mathbf{e}_{\mathbf{h}}(t-\tau-1) &= \mathbf{e}_{\mathbf{h}}(t-\tau)\mathbf{R}*(\overrightarrow{1}-\mathbf{h}(t-\tau-1)*\mathbf{h}(t-\tau-1)),\\ \tau\in[0,\,T) \text{ and } T: \# \text{ of unfolding steps.} \end{split}$$

Learning Algorithm(BPTT)

• The weight matrix ${\bm U}$ and the recurrent weights ${\bm R}$:

$$\mathbf{U}(t+1) = \mathbf{U}(t) - \alpha \left[\sum_{z=0}^{T-1} e_{\mathbf{h}}(t-z)^{T} i(t-z)\right]$$
$$\mathbf{R}(t+1) = \mathbf{R}(t) - \alpha \left[\sum_{z=0}^{T-1} e_{\mathbf{h}}(t-z)^{T} \mathbf{h}(t-z)\right]$$

Testing process



Figure: RNN testing process with sequential input samples.

• We only record the hidden state of the last test sample.

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Overall performance

- Data : Logs of search engine for 2 weeks (randomly sample a set of users)
- Metric
 - Area Under ROC Curve (AUC)
 - Relative Information Gain (RIG)

Model	AUC	RIG
LR	87.48%	22.30%
NN	88.51%	23.76%
RNN	88.94%	26.16%

Figure: Overall performance of models

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4. Experiments

Performance with History

- RNN model performs the best in all settings
- Long sequences help further improve the accuracy of CTR.



Figure: Performance with Long vs. Short History

4. Experiments

Effect of RNN Unfolding Step

- Unfolding 3 steps is the best.
- The backpropagated error vanishes after 3 steps of unfolding.